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PATENT

UNITED STATES PATENT APPLICATION  
FOR  
EXTENSIBLE GPS RECEIVER SYSTEM

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## EXTENSIBLE GPS RECEIVER SYSTEM

### BACKGROUND OF THE INVENTION

#### 5 FIELD OF THE INVENTION

The present invention relates to a mechanism for processing positioning signals such as those received from the Global Positioning System (GPS).

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#### ART BACKGROUND

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The global positioning system (GPS) has become extremely popular for a number of applications. GPS receivers are now incorporated into a variety of systems including consumer electronic systems in which the location information or time information provided by GPS supplements the other information provided by the system. Thus, more and more industries are realizing the advantages that GPS can provide.

Typically, when a customer, such as an original equipment manufacturer (OEM) develops a particular application of GPS, the GPS manufacturer generates the application code in accordance with the customer's specification. The GPS manufacturer designs and codes the user application of GPS, as the processing performed by the GPS receiver has strict timing and processing requirements that cannot be disturbed by other processing such as the user application processing. Unless carefully written, the execution of customer code can conflict with the GPS processing code. In addition, there is the danger of the user code overriding sections of memory



## SUMMARY OF THE INVENTION

The apparatus and method of the present invention provides a processing system in which the processor is coupled to a Global Positioning System (GPS) receiver circuitry that receives positioning signals and, in accordance with well known GPS processing techniques, generates the positioning data for access by a user application process executing on the same processor. A firewall is established between the user application process and the GPS process. The firewall prevents the user application process from conflicting with time critical processing by the GPS process and further prevents the user application process from overriding the memory areas allocated to the GPS process.

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## BRIEF DESCRIPTION OF THE DRAWINGS

The objects, features and advantages of the present invention will be apparent to one skilled in the art from the following detailed description in  
5 which:

**Figure 1** is a simplified block diagram of one embodiment of the system of the present invention.

**Figure 2** is a block diagram illustrating the structure of the processes in accordance with the teachings of the present invention.

10 **Figures 3a and 3b** illustrate one class of GPS objects in accordance with the teachings of the present invention.

**Figures 4a, 4b, 4c, 4d, 4e, 4f and 4g** illustrate another class of GPS objects in accordance with the teachings of the present invention.

15 **Figures 5a and 5b** illustrate a class of GPS objects in accordance with the teachings of the present invention.

## DETAILED DESCRIPTION

In the following description, for purposes of explanation, numerous details are set forth in order to provide a thorough understanding of the present invention. However, it will be apparent to one skilled in the art that these specific details are not required in order to practice the present invention. In other instances well known electrical structures and circuits are shown in block diagram form in order not to obscure the present invention unnecessarily.

The system of the present invention provides a user configurable Global Position System (GPS) receiver system in which the user application processing does not interfere with time critical positioning processing. A simplified block diagram is shown in **Figure 1**. The system and methods of the present invention are described below with reference to a GPS receiver. However, it is contemplated that the present invention can be implemented in a variety of positioning system receivers including GLONASS, Loran-C and Pseudo-lite receivers.

Referring to **Figure 1**, a GPS antenna and corresponding receiver circuitry **10** is connected to processor **15** via bus **20**. The processor **15** interacts with the GPS hardware such as the correlators, voltage control oscillator (VCO's) and the like, located in receiver **10** to acquire and track GPS signals transmitted by satellites. Thus, GPS receiver **10** receives GPS signals from satellites under the control of processor **15** acquires and tracks the satellites in order to receive the positioning signals. The processor **15** further processes the positioning signals to generate positioning data. Typically, the positioning data includes a time, angular and distance measurements. The specific data generated can vary according to implementation and is well

known in the art. Furthermore, the control functions performed by the processor to acquire and track signals are well known in the art and will not be discussed further herein.

As is well known in the art, positioning signal processing is time critical in nature. Therefore, delays in processing the positioning signals can cause significant error in the computations. Processor 15 not only performs position signal processing, but also performs user application processing. The code and data for the user application as well as the positioning signal code and data are preferably stored in memory 25, which is coupled to processor 15 via bus 20. It is contemplated that memory 25 may also be coupled to processor 15 through a separate bus (not shown). In addition, the system includes a variety of I/O devices, such as GPS antenna/receiver 10, a display 30 and at least one user input device input device 35, such as a keyboard or mouse. The use of these I/O devices is programmable according to the user application.

**Figure 2** is a block diagram illustrating the process structure that enables the positioning signal processing to be performed without encumbrance by the user application processing. The processor is controlled by an operating system which receives the instructions of the executing processes and controls the processor accordingly.

Although not limited as such, in the present embodiment it is preferred that a real-time operating system 205 is used to address the time critical nature of the satellite signal processing. The operating system 205 is connected to the code 210 used to control the input/output devices including the GPS receiver. One example of a real-time operating system is the Vx Works® embedded operating system marketed by WindRiver Systems. The processor processes the satellite signals in accordance with the

GPS process 215. Thus, GPS process 215 interacts in the real-time manner with the real-time operating system 205 to receive positioning signals through I/O control 210 and controls the GPS receiver circuitry through I/O control 210 to accurately acquire and track the satellite signals.

5 As noted above it is desirable to enable the user to configure the system for the user's particular application. Therefore, in order to provide this capability, a firewall <sup>250</sup>~~220~~ is established between the GPS process 215, real-time operating system 205, and the user application 225.

10 In the present embodiment a virtual machine is used 230 to provide a level of protection from a user application program interfering with the data utilized in the GPS process 215. For example, the virtual machine 230 prohibits the user application process 225 from specifically accessing or corrupting a particular memory location not previously allocated to that application as the virtual machine acquires the application to address a particular memory location using a virtual address. In addition, the application process must have the privilege of accessing that particular address. Thus, virtual machine 230 provides one level of the firewall 250.

20 A virtual machine is a software computer that executes programs that have been compiled into byte code. As noted above, the virtual machine separates the hardware and system software from the application software. Thus, system independent applications can be developed in any language that has a compiler that generates the virtual machine byte code. Applications once complied with byte code can be downloaded and executed as any processor that executes a virtual machine. One such virtual machine, 25 is the Java Virtual Machine, by Sunsoft, Mountain View, California.

The firewall 250 further is required to prohibit the user application 225 from interfering with the time critical processing of the GPS process 215.



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In order to protect against this potential problem, the user application processes, as executed by virtual machine 230, are set to a priority that is lower than the priority of the GPS process 215. For example, this is done by setting the priority of the GPS process to the highest priority in the operating system 205. Thus, any other process, such as the user application process will run at a lower priority, thus insuring that the GPS process 215 executes in a timely manner.

Continuing reference with **Figure 2**, in the present embodiment, an application programming interface (API) 240 is provided to simplify the user task of developing the user application. The API 240 preferably includes a number of functions that are accessible by the user application. In the present embodiment, the system is programmed using object oriented technology, such as C++; alternately the Java language can be used. **Figures 3a** and **3b** illustrate the Java objects for getting information to perform routing processes. **Figures 4a - 4g** illustrate objects used to acquire time information from GPS signals. **Figure 5a** is illustrative of GPSfix objects that can be used to get location information, i.e., a "fix". In the present embodiment, it is preferred that the GPSfix classes are constructed as class hardwarefix or simfix, wherein class hardwarefix, when initialized, includes communication between the class and the hardware. Furthermore, the object created receives data from the GPS hardware receiver. Simfix is a class of superclass GPSfix that users can instantiate to obtain a simulated GPS fix. When the class is initialized (e.g., the first time it is used), a simulator is started that propagates meaningful positions over time. Furthermore, the class includes methods to deal with simulation, e.g., defining regions and dynamics of simulated data. Simfix is used to provide an applications developer with a realistic model of GPS data.

